

9.6.99

(1)

Are our transformations canonical?  
 (Levi-Civita plus time transformation)

$$S = \int_{t_1}^{t_2} L(q_i, \dot{q}_i, t) dt$$

S: action integral  
L: Lagrange function

$\delta S = 0$  defines physical motion  
 (least action principle, Hamilton's  
 variational princ.)

$$\delta S = \int_{t_1}^{t_2} \sum_i \left( \frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right) dt = \text{(partial integr.)}$$

(Variat. of boundary terms vanishes)

$$= \int_{t_1}^{t_2} \sum_i \left( \frac{\partial L}{\partial q} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} \right) \delta q dt$$

For all  $\delta q_i \Rightarrow$  Euler-Lagrange Eq. of motion!

$$H = \sum_i p_i \dot{q}_i - L \Leftrightarrow L = \sum_i p_i \dot{q}_i - H$$

$$0 = \delta S = \int_{t_1}^{t_2} \sum_i \left( \dot{q}_i \delta p_i + p_i \delta \dot{q}_i - \frac{\partial H}{\partial p_i} \delta p_i - \frac{\partial H}{\partial q_i} \delta q_i \right) dt$$

$$= \int_{t_1}^{t_2} \left[ \left( \dot{q}_i - \frac{\partial H}{\partial p_i} \right) \delta p_i - \left( p_i + \frac{\partial H}{\partial q_i} \right) \delta q_i \right] dt$$

For all  $\delta q_i, \delta p_i \Rightarrow$  Hamilton's Eq. of motion.

(2)

Canonical Transformation  $\Leftrightarrow$  $\Leftrightarrow$  Hamilton's Eq. of motion invariant

$$\delta \int_{t_1}^{t_2} \left( \sum_{i=1}^3 p_i \dot{q}_i - H \right) dt = 0 \quad \text{in both systems of variables.}$$

1) Levi-Civita transformation

$$\sum_{i=1}^3 p_i \dot{q}_i = \sum_{i=1}^3 v_i \dot{r}_i = \sum_{i=1}^3 v_i^2 \quad \begin{array}{l} p_i = v_i \\ q_i = r_i \end{array}$$

Let  $Q_i = u_i$ ,  $P_i = 4u^2 \dot{u}_i$  Levi-Civita variables

$$\sum_{i=1}^4 P_i \dot{Q}_i = 4u^2 \sum_{i=1}^4 \dot{u}_i^2 = \sum_{i=1}^3 v_i^2 = \sum_{i=1}^3 p_i \dot{q}_i$$

$$\text{Since } \sum_{i=1}^3 v_i^2 = \sum_{i=1}^4 4u^2 \dot{u}_i^2 \quad \text{see before}$$

2) Time transformation  $dt = g(Q, t) ds$ 

$$\delta S = \delta \int_{t_1}^{t_2} \left( \sum_{i=1}^3 p_i \dot{q}_i - H(p, q) \right) dt = \delta \int_{s_1}^{s_2} \left( \sum_{i=1}^4 P_i \dot{Q}_i - H(p, Q) \right) dt$$

$$= \delta \int_{s_1}^{s_2} \left( \frac{1}{g} \sum_{i=1}^4 P_i \dot{Q}_i - H(p, Q) \right) g ds$$

$$\dot{Q}_i' = \frac{\partial Q_i}{\partial s} = \frac{\partial Q_i}{\partial t} \frac{dt}{ds} = \dot{Q}_i g; \quad \Gamma = g(H - h) = \delta \int_{s_1}^{s_2} \left( \sum_{i=1}^4 P_i \dot{Q}_i' - \Gamma \right) ds$$

(3)

$p_i, q_i, H(p_i, q_i, t), t$  satisfies Hamilton's eq.

$\Leftrightarrow$   
 $P_i, Q_i, \Gamma(P_i, Q_i, s), s$  satisfies Hamilton's eq.

$\Gamma$ : Poincaré transform of Hamiltonian

$$\Gamma = g \left( H - \frac{h}{\mu} \right) \quad dt = g \cdot ds$$

Our example:  $g = r = u^2 = \sum_{i=1}^4 u_i^2$

$$H = \frac{1}{2} \sum_{i=1}^3 v_i^2 - \frac{G_{\omega_1 \omega_2}}{\mu r} = 2u^2 \sum_{i=1}^4 \dot{u}_i^2 - \frac{G_{\omega_1 \omega_2}}{\mu u^2}$$

$$\begin{aligned} \Gamma = r \cdot \left( H - \frac{h}{\mu} \right) &= 2u^4 \sum_{i=1}^4 \dot{u}_i^2 - \frac{G_{\omega_1 \omega_2}}{\mu} - \frac{h}{\mu} u^2 \\ &= \sum_{i=1}^4 \left( \frac{P_i^2}{8} - \frac{h}{\mu} Q_i^2 \right) - \frac{G_{\omega_1 \omega_2}}{\mu} \end{aligned}$$

Canonical Equations:

$$Q_i' = \frac{\partial \Gamma}{\partial P_i} = \frac{P_i}{4} \Leftrightarrow u_i' = u^2 \dot{u}_i = r \dot{u}_i \quad \text{O.K.}$$

$$P_i' = - \frac{\partial \Gamma}{\partial Q_i} = 2 \frac{h}{\mu} Q_i \Leftrightarrow (4u^2 \dot{u}_i)' = 4u_i'' = 2 \frac{h u_i}{\mu}$$

$u_i'' - \frac{h}{2\mu} u_i = 0$	$u_i'' + \frac{ h }{2\mu} u_i = 0 \quad (h < 0)$
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