

The issue about accuracy!

- Simulation uses: $10^6 - 10^{10}$ steps, N force calculations per step; $N = 10^6 \sim 10^{12} = 10^{16}$ force (pairwise) calculations
- Double precision $\sim 10^{-13}$ - if all errors sum up in a "bad" way \rightarrow final error 'order unity'

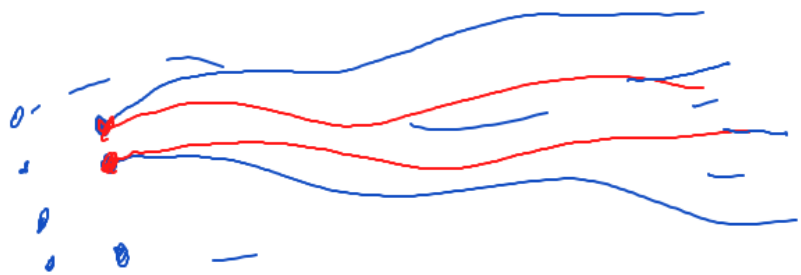
In our simulations it is not^{so} serious:

1) errors are often uncorrelated! r.m.s. error $\ll \sum |error|$!
(depending on system symmetry) Care: for strongly asymm. systems!

2) What can we check? * total energy (Makino 1991)
ADJUST!!

What else? Total Angular Momentum (three vector components)
We can only look for globally conserved quantities!

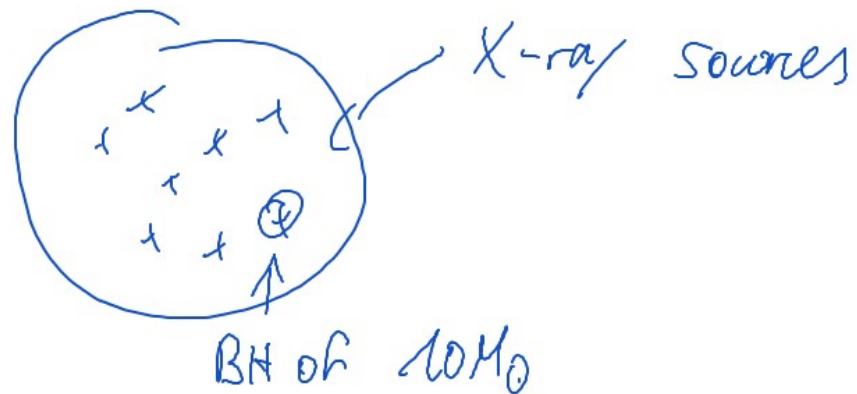
3) Miller, R. 1964: exponential divergence of orbits
coming from very small differences of initial pos./vel.
N-body meaningless?? See Quinlan+Tremaine (1992)
numerical *N-body* simulation: trajectories of particles
stay always close to a real Hamiltonian solution!



*no contradiction
to exponential divergence!*

• star clusters, glob. cl., 1M particles

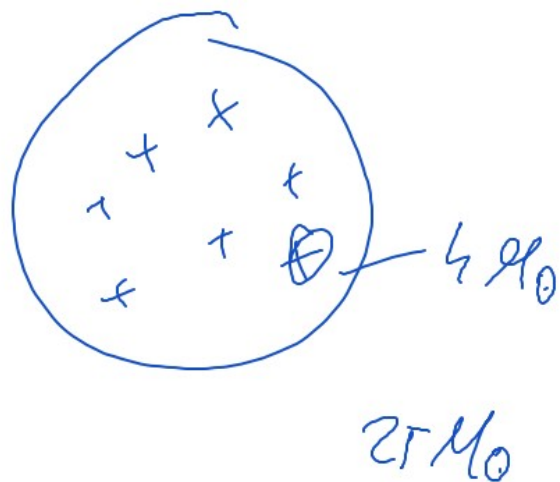
47 Tuc



BH of 10M_⊙

Giersz + Spurzem (1994)

Simulation



25M_⊙

General Features of the Code

- Hermite Scheme + hierarchically blocked time steps
- Ahmad - Cohen Neighbour neighbour scheme
- Regularisations: close 2, 3, few-body, subsystem
(classical, algorithmic)
- Stellar Evolution

Comparison of the code versions

| | ITS | ACS | KS | HITS | PN | AR | CC | MPI | GPU |
|-------------|-----|-----|----|------|----|----|----|-----|-----|
| NBODY1 | ✓ | | | | | | | | |
| NBODY2 | | ✓ | | ✓ | | | | | |
| NBODY3 | ✓ | | ✓ | | | | | | |
| NBODY4 | | | ✓ | ✓ | | | | | |
| NBODY5 | ✓ | ✓ | ✓ | | | | | | |
| NBODY6 | | ✓ | ✓ | ✓ | | | | | |
| NBODY6GPU | | ✓ | ✓ | ✓ | | | | ✓ | |
| NBODY6++ | | ✓ | ✓ | ✓ | | | ✓ | | |
| NBODY6++GPU | | ✓ | ✓ | ✓ | ✓ | | ✓ | ✓ | ✓ |
| NBODY7 | | ✓ | ✓ | ✓ | ✓ | ✓ | | | ✓ |

From:
 Spurzem &
 Kamlah (2023);
 subm. to
 Living Reviews
 on
 Computational
 Astrophysics
 (LRCA)

ITS: Individual time-steps [107] **Aarseth (1985)**

ACS: Ahmad-Cohen neighbour scheme [109] **Ahmad & Cohen (1973)**

KS: KS-regularization of few-body subsystems [104] **Kustaanheimo & Stiefel (1965)**

HITS: Hermite scheme integration method combined with hierarchical block time-steps [111]

PN: Post-Newtonian [Kupi et al. (2006), Brem et al. (2013)] **Makino & Aarseth (1992)**

AR: Algorithmic regularization **Mikkola & Tanikawa (1999ab)**, w/PN: **Mikkola & Merritt (2008)**

CC: Classical chain regularization. **Mikkola & Aarseth (1990, 1993, 1998)**, w/PN: **Aarseth (2012)**

MPI: Message Passing Interface, multi-node multi-CPU parallelization [139] **Spurzem (1999)**

GPU: use of GPU acceleration [138] (if also MPI: multi-node many GPU [144])

Nitadori & Aarseth (2012), Berczik et al. (2013)

NBODY7: Aarseth (2012), Banerjee et al. (2020)

Hemite Scheme: acceleration \vec{a}_i ; force $\vec{F}_i = m_i \vec{a}_i$ | $\bullet = \frac{d}{dt}$

particle i ; all other particle j
 position vector \vec{r}_i ; $\vec{v}_i = \dot{\vec{r}}_i$; Newton's Law:

$$\vec{a}_i = -G \sum_{\substack{j=1 \\ j \neq i}}^N m_j \frac{\vec{r}_i - \vec{r}_j}{|\vec{r}_i - \vec{r}_j|^3};$$

for Hemite:

$$\vec{a}_i = -G \sum_{\substack{j=1 \\ j \neq i}}^N m_j \left[\frac{\vec{v}_i - \vec{v}_j}{|\vec{r}_i - \vec{r}_j|^3} - \frac{(\vec{R}_{ij} \cdot \vec{V}_{ij})(\vec{r}_i - \vec{r}_j)}{|\vec{r}_i - \vec{r}_j|^5} \right]$$

$\vec{R}_{ij} = \vec{r}_i - \vec{r}_j$; $\vec{V}_{ij} = \vec{v}_i - \vec{v}_j$ $\vec{r}_i = (x_i, y_i, z_i)$

$$|\vec{r}_i - \vec{r}_j|^2 = (x_i - x_j)^2 + (y_i - y_j)^2 + (z_i - z_j)^2$$

Unit Vector
 $(\vec{r}_i - \vec{r}_j)$
 (\quad)
 Coefficient
 $\vec{r}_i \vec{r}_j$

Low Order Taylor series for prediction:

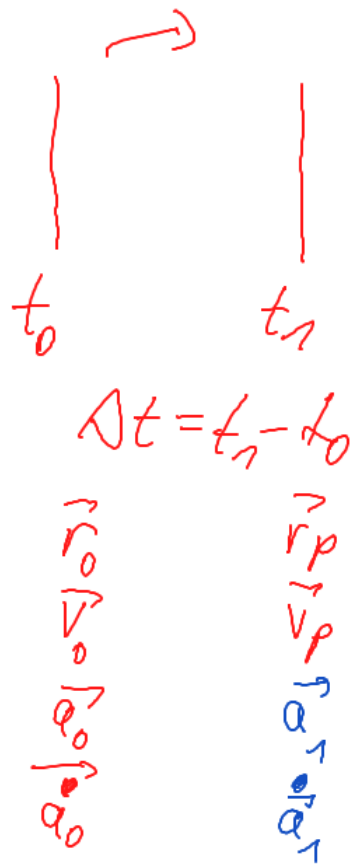
$$\vec{r}_p(t_1) = \vec{r}_0 + \vec{v}_0 \cdot \Delta t + \frac{1}{2} \vec{a}_0 \Delta t^2 + \frac{1}{6} \vec{a}_0^{\circ} \Delta t^3 + \mathcal{O}(\Delta t^4)$$

(Assume that we sit our particle i ! $\vec{r}_0 = \vec{r}_{0i}$ Drop i)

$$\vec{v}_p(t_1) = \vec{v}_0 + \vec{a}_0 \Delta t + \frac{1}{2} \vec{a}_0^{\circ} \Delta t^2 + \mathcal{O}(\Delta t^3)$$

2nd order accurate, Error $\mathcal{O}(\Delta t^3)$

Hermite trick is to compute $\vec{a}_1, \vec{a}_1^{\circ}$
in two ways!



1) Newton's law with predicted ^{velocities} + positions of all particles!

$$\vec{a}_1 = -G \sum_{\substack{j=1 \\ j \neq i}}^N m_j \frac{\vec{r}_p - \vec{r}_{pj}}{|\vec{r}_p - \vec{r}_{pj}|^3} \quad \text{and} \quad \dot{\vec{a}}_1 \text{ using } \vec{v}_{pj}, \dot{\vec{v}}_{pj}$$

2) Use Taylor Series to approximate $\vec{a}_1, \dot{\vec{a}}_1$:

$$\vec{a}_1 = \vec{a}_0 + \dot{\vec{a}}_0 \Delta t + \frac{1}{2} \vec{a}_0^{(2)} \Delta t^2 + \frac{1}{6} \vec{a}_0^{(3)} \Delta t^3 + O(\Delta t^4)$$

$$\dot{\vec{a}}_1 = \dot{\vec{a}}_0 + \ddot{\vec{a}}_0 \Delta t + \frac{1}{2} \dot{\vec{a}}_0^{(3)} \Delta t^2 + O(\Delta t^3)$$

Two ^{Known} unknowns, two equations!

$$\vec{a}_0^{(2)} = \left[\underbrace{-3(\vec{a}_0 - \vec{a}_1)}_{O(\Delta t^4)} - \underbrace{(2\vec{a}_0 + \vec{a}_1) \cdot \Delta t}_{O(\Delta t^3) = O(\Delta t)} \right] \frac{2}{\Delta t^2} + O(\Delta t^2)$$

$$\vec{a}_0^{(3)} = \left[2(\vec{a}_0 - \vec{a}_1) + (\vec{a}_0 + \vec{a}_1) \cdot \Delta t \right] \frac{6}{\Delta t^3} + O(\Delta t)$$

Corrected: Hermite Formula for $a_0^{(2)}, a_0^{(3)}$

$$\vec{r}_c(t) = \vec{r}_p(t) + \frac{1}{24} \vec{a}_0^{(2)} \Delta t^4 + \frac{1}{120} \vec{a}_0^{(3)} \Delta t^5 + O(\Delta t^6)$$

$$\vec{v}_c(t) = \vec{v}_p(t) + \frac{1}{6} \vec{a}_0^{(2)} \Delta t^3 + \frac{1}{24} \vec{a}_0^{(3)} \Delta t^4 + O(\Delta t^5)$$

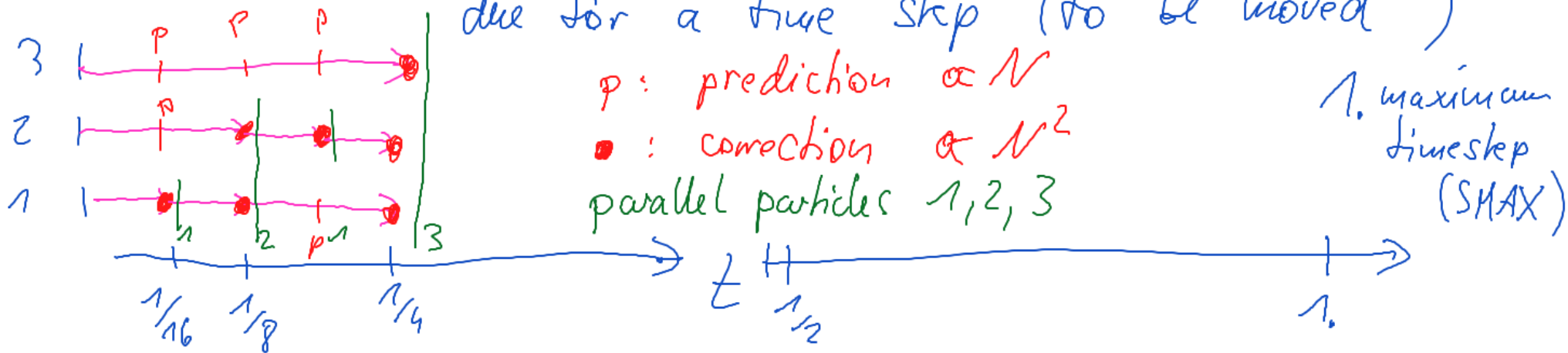
Global Error is $O(\Delta t^5)$!

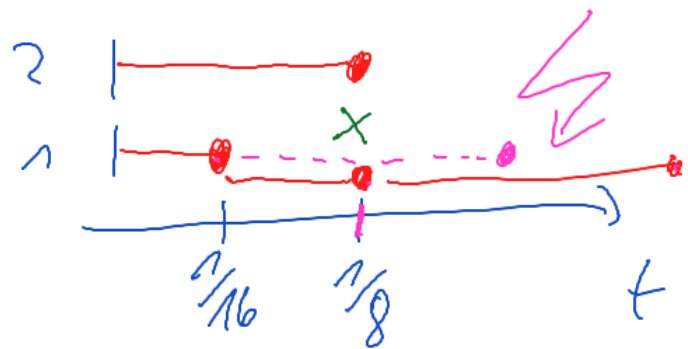
t_0 ————— t_1
 $\vec{r}_0, \vec{v}_0, \vec{a}_0$ ————— $\vec{r}_1, \vec{v}_1, \vec{a}_1$
 $\vec{a}_0^{(2)}$
 $\vec{a}_0^{(3)}$

— Hermite Scheme : $\begin{matrix} \text{2nd order} \\ \text{Predictor} - \\ \mathcal{O}(\Delta t^3) \end{matrix} \quad \begin{matrix} \text{4th order} \\ \text{Corrector} \\ \mathcal{O}(\Delta t^5) \end{matrix}$

— Hierarchically Blocked Time Step Scheme :

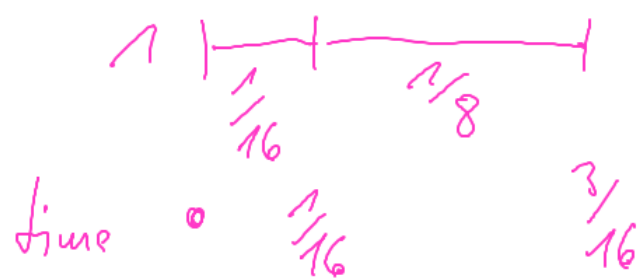
- Predictor is always done for all particles
- Corrector is only done for particles which are due for a time step (to be moved)





x: particle one would miss
the parallel correction
at $t = \frac{1}{8}$!

Demand: Time and Step are commensurate
 $\text{TIME} / \Delta t \hat{=} \text{integer}$



Step: $\frac{2}{16} = \frac{1}{8}$
Time: $\frac{3}{16}$

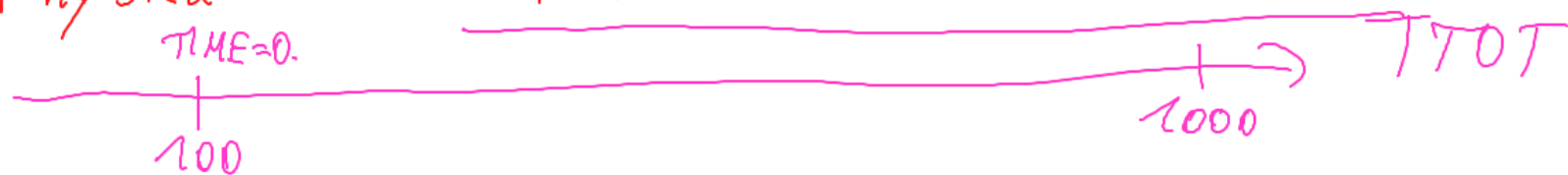
} $\frac{\text{TIME}}{\text{Step}} \neq \text{integer}$

Hierarchically Blocked ITS (HITS)

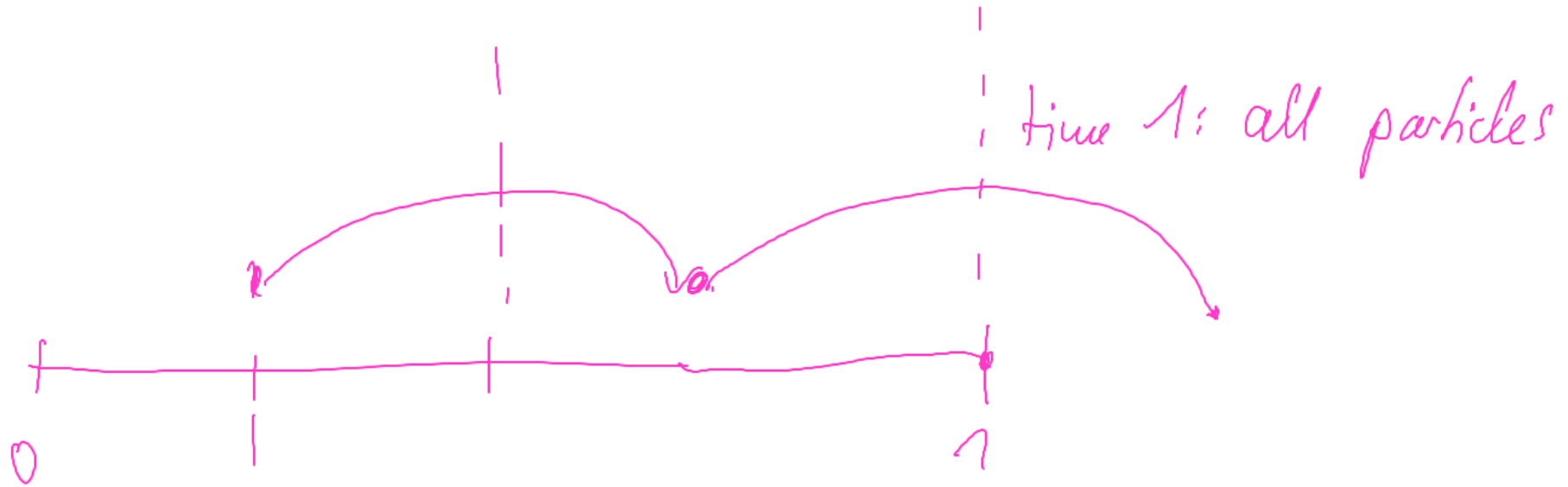
- 1: $\Delta t = \frac{1}{2^n}$, $n = 0, \dots, 32, \dots$
- 2: $\text{DMOD}(\text{TIME}, \text{STEP} \underset{R}{I}) = \phi \cdot D \phi$

(We do not allow TIME to grow too large!
 $\text{TIME} < \text{DTOFF} \sim 100$.)

Physical Time: $\text{TTOT} = \text{TIME} + \text{TOFF}$



In that way: we get maximum number of parallel connections! $S_{MAX} = 1.0$





Sequential: $\underbrace{\text{H} \rightarrow \text{H} \rightarrow \text{H}}_1 \text{--- Million} \rightarrow$

To reach $1/8$: $\text{Million} + 3$



Speedup ~ 100